Specific Loss Power in Magnetic Hyperthermia: Comparison of Monodispersion and Polydispersion

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Abstract

Magnetic hyperthermia (MH) is a promising approach to cancer therapy that uses the heat released by magnetic nanoparticles (MNPs) under an alternating magnetic field (AMF). Since the existence of some size polydispersity of MNPs is experimentally unavoidable, the size polydispersity is important for achieving an accurate control of the heating performance of MNPs. The purpose of this study was to investigate the effect of the size polydispersity on the specific loss power (SLP) in MH under various conditions of MNPs, AMF, and static magnetic field (SMF). The SLP value in the quasi steady state (SLP_{qss}) for the polydisperse case was computed using the probability density function based on a log-normal distribution. The SLP_{ass} value was largely affected by the size polydispersity and its dependency on the size polydispersity changed depending on the magnetic and physical properties of MNPs and the parameters of AMF. The plot of the SLP_{qss} values against the position from a field-free pointwas also affected by the size polydispersity.Our resultssuggest that it is essential to consider the size polydispersity for the accurate estimation of SLP and for accurately controlling the temperature rise and the area of local heating in MHusing SMF.

Keywords —*Magnetic hyperthermia, magnetic nanoparticle, specific loss power, monodispersion, polydispersion, log-normal distribution.*

I. INTRODUCTION

Magnetic hyperthermia is a promising approach to cancer therapy that uses the heat released by magnetic nanoparticles (MNPs) under an alternating magnetic field (AMF) to treat tumors [1]-[3]. With the development of precise methods for synthesizing functionalized MNPs [4], MNPs with functionalized surfaces, which have high specificity for tumors, have been developed as heating elements for magnetic hyperthermia [5]. Recently, MNPs with a higher heating efficiency, *i.e.*, specific loss power (SLP) have also been actively developed [6].

The estimation of SLP is important for evaluating the heating efficiency of MNPs, for optimizing the parameters of AMF, and for the optimal design of MNPs in an attempt to establish the effectiveness of magnetic hyperthermia [7], [8].It is

also important to heat the targeted tumor to the desired temperature without damaging the surrounding healthy tissues in order to enhance the effectiveness of magnetic hyperthermia [7], [8]. Tasci *et al.* [9] proposed and designed a system that focuses the heat into very small regions using a static magnetic field (SMF) with a field-free point (FFP) generated by two solenoid coils, and reported that this method will be useful for making magnetic hyperthermia a more effective approach to cancer therapy with a decreased risk of heating surrounding healthy tissues. We have also investigated the usefulness of this method and reported that it is useful for controlling the temperature rise in magnetic hyperthermia [10].

Recently, we have presented methods for estimating SLP and compared the SLP values estimated by these methods under various conditions of MNPs and AMF [8]. Furthermore, we have also presented a method for estimating the SLP in the presence of both the AMF and SMF [11], which was based on the numerical solution of the magnetization relaxation equation of Shliomis [12].In our previous papers [8], [11], however, the particle size distribution was assumed to be monodisperse. As pointed out by Munoz-Menendez et al. [13], [14], the existence of some size polydispersity of MNPs is experimentally unavoidable, resulting in a different hyperthermia performance depending on the size of each MNP. Thus, the size polydispersity of MNPs is one of the important issues to achieve an accurate control of the heating performance of MNPs.

Our purpose in this study was to investigate the effect of the size polydispersityon the SLP in magnetic hyperthermia in comparison with the monodisperse case under various conditions of MNPs, AMF, and SMF.

II. MATERIALS AND METHODS

A. Theory

The magnetization relaxation equation of Shliomis [12], [15] is given by

$$\frac{d\mathbf{M}}{dt} = \mathbf{\Omega} \times \mathbf{M} - \frac{\mathbf{M} - \mathbf{M}_0}{\tau} - \frac{\mathbf{M} \times (\mathbf{M} \times \mathbf{H})}{6n\phi}, (1)$$

Where **M** is the magnetization of MNPs under the magnetic field **H**, Ω is the flow velocity, ϕ is the volume fraction, and η is the viscosity of the suspending fluid. When there is no bulk flow and **M**

and \mathbf{H} are collinear, Eq. (1) is reduced to the following equation [7]:

$$\frac{dM(t)}{dt} = -\frac{M(t) - M_0(t)}{\tau}.$$
 (2)
In Eq. (2), τ is the effective relaxation time given by

 $\frac{\tau}{\tau} = \frac{\tau}{\tau_N} + \frac{\tau}{\tau_B}, (3)$ where τ_N and τ_B are the Néel relaxation and Brownian relaxation time, respectively [6]. τ_N and τ_B are given by the following relationships [7]:

$$\tau_N = \tau_0 \frac{\sqrt{\pi}e^{\Gamma}}{2\sqrt{\Gamma}}$$
(4)
and

 $\tau_B = \frac{3\eta V_H}{k_B T},$ (5)

respectively, where τ_0 is the average relaxation time in response to a thermal fluctuation, $k_{\rm B}$ is the Boltzmann constant, T is the temperature, and $\Gamma = KV_M/(k_BT)$, with K being the anisotropy constant of MNP. $V_{\rm H}$ is taken as the hydrodynamic volume of MNP that is larger than the magnetic volume V_M = $\pi D^3/6$ for MNP of diameter D. As a model for V_H, it is assumed that $V_H = (1 + 2\delta / D)^3 V_M$, where δ is the thickness of a sorbed surfactant layer [6]. $M_0(t)$ in Eq. (2) denotes the equilibrium magnetization and is given by

$$M_0(t) = \chi_0 H(t), \tag{6}$$

where χ_0 and H(t) are the equilibrium susceptibility and magnetic field strength at time t, respectively. In this study, H(t) was assumed to be

 $H(t) = H_0 \cos(2\pi f t) + H_s,$ (7)where H_0 and f denote the amplitude and frequency of AMF, respectively, and H_s denotes the strength of an external SMF. Because the actual equilibrium susceptibility (χ_0) is dependent on the magnetic field, χ_0 was assumed to be the chord susceptibility corresponding to the Langevin equation, given by [7]

$$\chi_0 = \chi_i \frac{3}{\xi} (\operatorname{coth} \xi - \frac{1}{\xi}), \qquad (8)$$

where χ_i is the initial susceptibility given by $\chi_i =$ $\mu_0 \phi M_d^2 V_M / (3k_B T)$, ξ is the Langevin parameter given by $\xi = \mu_0 M_d H V_M / (k_B T)$, M_d is the domain magnetization of a suspended particle, and μ_0 is the permeability of free space. It should be noted that ξ is magnetic field dependent and thus time dependent.

Solving Eq. (2) and using Eq. (6) and Eq. (7) yield [8], [11]

$$M(t) = \frac{1}{\tau} e^{-\frac{t}{\tau}} \otimes M_0(t) + M(0) e^{-\frac{t}{\tau}} = \frac{1}{\tau} e^{-\frac{t}{\tau}} \otimes M_0(t) + \frac{1}{\tau} \otimes M_0(t) + \frac{$$

 $\chi_0[H_0\cos(2\pi ft) + H_s] + M(0)e^{-\tau}, \ (9)$ where \otimes denotes the convolution integral and M(0) is M(t) at t = 0. In this study, M(0) was assumed to be $M(0) = M_0(0) = \chi_0(H_0 + H_s)$. When $t = \infty$, however, the second term of the right-hand side of Eq. (9) can be neglected.

The average rate of energy dissipation per cycle of the period, *i.e.*, $1/f(\langle P \rangle)$ is given by [7]

$$\langle P \rangle = -\mu_0 f \int_0^{1/f} M(t) \frac{dH(t)}{dt} dt.$$
(10)
Substituting Eq. (7) into Eq. (10) yields

 $\langle P \rangle = 2\pi\mu_0 H_0 f^2 \int_0^{1/f} M(t) \sin(2\pi f t) dt .$ (11)The rate of energy dissipation per unit mass of MNPs, *i.e.*, SLP can be obtained from $\langle P \rangle$ as [8], [11]

$$SLP = \frac{\langle P \rangle}{\phi \rho},$$
 (12)

where ρ is the density of suspending fluid.

Because M(t) given by Eq. (9) must be timeperiodic in the steady state, the SLP value for the *i*-th cycle (SLP_i) can be given by [8], [11]

$$SLP_{i} = \frac{2\pi\mu_{0}H_{0}f^{2}}{\phi\rho} \left\{ \int_{(i-1)/f}^{i/f} \left[\frac{1}{\tau} e^{-\frac{t}{\tau}} \otimes M_{0}(t) \right] \sin(2\pi f t) dt + 2\pi f \tau 2M 01 + 2\pi f \tau 2e - if \tau (e1f\tau - 1) . (13) \right\}$$

It should be noted that when *i* is sufficiently large, the second term of the right-hand side of Eq. (13) can be neglected and SLP_i approaches the steady state. We denote the *SLP_i* value in the quasi steady state by SLP_{qss} . Actually, SLP_{qss} was taken as the SLP_i value in the case when the relative error given by $|SLP_i - SLP_{i-1}|/SLP_{i-1}$ was less than 10^{-10} [11]. The integration in Eq. (13) was performed by use of the trapezoidal rule [17] ("trapz" in MATLAB[®]; The MathWorks, Inc., Natick, MA, USA) and the convolution integral was calculated using the MATLAB[®] function ("conv").

Because not all particles in a certain volume have the same diameter Din the polydisperse case [13], [14], the SLP_{qss} value calculated from Eq. (13) should be averaged based on the particle size distribution as $\langle c_{I} p \rangle = \int_{\infty}^{\infty} c_{I} p$ ת הישתת

$$(SLP_{qss}) = \int_0 SLP_{qss} \cdot PDF(D)dD$$
, (14)
where $PDF(D)$ denotes the probability density
function of the particle size distribution. The result of
a natural growth process during particle synthesis does
not yield particles with a single diameter *D*, but with a
polydisperse particle size distribution. A reasonable
and commonly used approach for modeling is the log-
normal distribution [17]. In this case, $PDF(D)$ is
given by

$$PDF(D) = \frac{1}{\sqrt{2\pi\sigma}} \cdot \exp\left[-\frac{1}{2}\left(\frac{\ln(D)-\mu}{\sigma}\right)^2\right], \quad (15)$$

where μ and σ denote the mean and standard deviation of the natural logarithm of D, respectively, and are given by $\mu = \ln(mD) - \frac{1}{2}\ln\left(\frac{sD^2}{mD^2} + 1\right)(16)$

and

n

a

n

$$\sigma = \sqrt{\ln\left(\frac{sD^2}{mD^2} + 1\right)},$$
 (17)

respectively.mD and sD denote the mean and standard deviation of D, respectively. When mD and σ are known, sD is given by

$$sD = mD \cdot \sqrt{e^{\sigma^2} - 1}.$$
 (18)

The derivative of (SLP_{ass}) with respect to D is given hv

$$\frac{d\langle SLP_{qss}\rangle}{dD} = SLP_{qss} \cdot PDF(D).(19)$$



Fig. 1:Probability density function given by Eq. (15) as a function of the diameter of magnetic nanoparticles (MNPs) (*D*) for various σ (standard deviation of the natural logarithm of *D*) values (0.1, 0.2, 0.3, 0.4, and 0.5).

It should be noted that when σ approaches zero, PDF(D) given by Eq. (15) approaches $\delta(D - mD)$, where $\delta(*)$ denotes the so-called Dirac's delta function. When $\sigma = 0$, $\langle SLP_{qss} \rangle$ given by Eq. (14) corresponds to the SLP_{qss} value for the monodisperse case, which is denoted by SLP_{qss}^{mono} in this study.

B. Simulation Studies

In this study, we assumed that MNPs consisted of two kinds of iron oxide nanoparticles, *i.e.*, maghemite (γ -Fe₂O₃) and magnetite (Fe₃O₄). We fixed τ_0 , δ , M_d , K, η , ρ , ϕ , and Tto be 10⁻⁹ s, 2 nm, 414 kA/m, 4.7 kJ/m³, 0.00235 kg/m/s, 4600 kg/m³, 0.003, and 37 °C, respectively, for maghemite [17], [18]. For magnetite, we fixed τ_0 , δ , M_d , K, η , ρ , ϕ , and Tto be 10⁻⁹ s, 2 nm, 446 kA/m, 9.0 kJ/m³, 0.00235 kg/m/s, 5180 kg/m³, 0.003, and 37 °C, respectively [18]. When H_0 , f, and mD were fixed, they were taken as 20 mT, 300 kHz, and 20 nm, respectively.It should be noted that the unit of mT can be converted to kA/m by use of the relationship 1 mT=0.796 kA/m.

When considering the control of the temperature rise using the SMF with a gradient strength of G_s , the strength of the SMF at a distance of *x* from the FFP ($H_s(x)$) was given by $H_s(x) = G_s \times x[11]$.

III.RESULTS

Fig. 1 shows *PDF*(*D*) given by Eq. (15) as a function of *D* for various σ values (0.1, 0.2, 0.3, 0.4, and 0.5). Fig. 2 shows the derivative of the specific loss power in the quasi steady state with respect to $D(d\langle SLP_{qss} \rangle/dD)$ calculated from Eq. (19) as a function of *D* for various σ values (0.1, 0.2, 0.3, 0.4, and 0.5). Fig. 2(a) and Fig. 2(b) show cases for maghemite and magnetite, respectively. In these simulations, H_0 , *f*, *mD*, and H_s were assumed to be 20 mT, 300 kHz, 20 nm, and 0 mT, respectively. As shown in Fig. 2, the plots for maghemite had peaks between D = 22 nm and D = 25 nm (Fig. 2(a)), whereas those for magnetite had peaks near D =



Fig. 2:Derivative of the specific loss power in the quasi steady state with respect to $D (d\langle SLP_{qss} \rangle/dD)$ calculated from Eq. (19) as a function of D for various σ values (0.1, 0.2, 0.3, 0.4, and 0.5). (a) for maghemite and (b) for magnetite. In these simulations, the amplitude (H_0) and frequency (f) of an alternating magnetic field (AMF), mean diameter of MNPs (mD), and strength of a static magnetic field (H_s) were assumed to be 20 mT, 300 kHz, 20 nm, and 0 mT, respectively. Note that the unit of mT can be converted to kA/m by use of the relationship 1 mT=0.796 kA/m.The magnetic and physical properties of maghemite and magnetite used in this study are described in the "Simulation Studies" section.

20 nm (Fig. 2(b)). Although the height, width, and position of the peaks differed between maghemite (Fig. 2(a)) and magnetite (Fig. 2(b)), the height of the peaks decreased with increasing σ value in both cases.

Fig. 3(a) shows the $\langle SLP_{qss} \rangle$ value calculated from Eq. (14) as a function of σ for various *mD* values (10, 15, 20, 25, and 30 nm) for maghemite, whereas Fig. 3(b) shows the $\langle SLP_{qss} \rangle$ value divided by the SLP_{qss} value for the monodisperse case (SLP_{qss}^{mono}) ($\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$) as a function of σ for various *mD* values (10, 15, 20, 25, and 30 nm). Fig. 4 shows those for magnetite. In these simulations, H_0 , f, and H_s were assumed to be 20 mT, 300 kHz, and 0 mT, respectively. As shown in Fig.3andFig. 4, the dependencies of $\langle SLP_{qss} \rangle$ and $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ on σ changed largely depending on *mD*. In the case of maghemite (Fig. 3), when *mD* was 25 nm, both



Fig. 3:(a) Specific loss power in the quasi steady state calculated from Eq. (14) ($\langle SLP_{qss} \rangle$) as a function of ofor various *mD* values (10, 15, 20, 25, and 30 nm) for maghemite; (b) $\langle SLP_{qss} \rangle$ divided by the specific loss power in the quasi steady state for the monodisperse case (SLP_{qss}^{mono}) ($\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$) as a function of ofor various *mD* values (10, 15, 20, 25, and 30 nm) for maghemite. In these simulations, H_0 , f, and H_s were assumed to be 20 mT, 300 kHz, and 0 mT, respectively.

 $\langle SLP_{qss} \rangle$ and $\langle SLP_{qss} \rangle/SLP_{qss}^{mono}$ decreased almost monotonically with increasing σ value. When mDdeviated from 25 nm, they increased with increasing σ value, making peaks, and then decreased thereafter. The σ valuesat which they had peaks changed depending on mD. In the case of magnetite (Fig. 4), when mD was 20 nm, both $\langle SLP_{qss} \rangle$ and $\langle SLP_{qss} \rangle/SLP_{qss}^{mono}$ decreased almost monotonically with increasing σ value. When mD deviated from 20 nm, they increased with increasing σ value, making peaks, and then decreased thereafter.

Fig. 5(a)and Fig. 5(b)show the (SLP_{qss}) and $(SLP_{qss})/SLP_{qss}^{mono}$ values, respectively, as a function of σ for various H_0 values (5, 10, 15, 20, and 25 mT) for maghemite. Fig. 6 shows those for magnetite. In these simulations, f, mD, and H_s were assumed to be 300 kHz, 20 nm, and 0 mT, respectively. In the case of 5), both $\langle SLP_{ass} \rangle$ maghemite (Fig. and $(SLP_{qss})/SLP_{qss}^{mono}$ had peaks between $\sigma = 0.1$ and almost $\sigma = 0.2$, whereas they decreased



Fig. 4:(a) $\langle SLP_{qss} \rangle$ as a function of σ for various *mD* values (10, 15, 20, 25, and 30 nm) for magnetite; (b) $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ as a function of σ for various *mD* values (10, 15, 20, 25, and 30 nm) for magnetite. In these simulations, H_0 , *f*, and H_s were assumed to be 20 mT, 300 kHz, and 0 mT, respectively.

monotonically with increasing σ value in the case of magnetite (Fig. 6). The $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ value did not largely depend on H_0 in both cases (Fig. 5(b) and Fig. 6(b)).

Fig. 7(a)and Fig. 7(b)show the $\langle SLP_{qss} \rangle$ and $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ values, respectively, as a function of σ for various *f* values (200, 400, 600, 800, and 1000 kHz) for maghemite. Fig. 8 shows those for magnetite.In these simulations, H_0 , *mD*, and H_s were assumed to be 20 mT, 20 nm, and 0 mT, respectively.As shown in Fig. 7 and Fig. 8, both $\langle SLP_{qss} \rangle$ and $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ changed largely depending on *f* in both cases, and their dependencies on *f* differed between maghemite (Fig. 7) and magnetite (Fig. 8).

Fig. 9(a)and Fig. 9(b)show the $\langle SLP_{qss} \rangle$ and $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ values, respectively, as a function of σ for various H_s values (0, 10, 20, 30, and 40 mT) for maghemite. Fig. 10 shows those for magnetite.In these simulations, H_0 , f, and mD were assumed to be 20 mT, 300 kHz, and 20 nm, respectively.In the case of maghemite (Fig. 9), both $\langle SLP_{qss} \rangle$ and $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ had peaks between $\sigma = 0.1$ and $\sigma = 0.2$, whereas they decreased almost



Fig. 5:(a) $\langle SLP_{qss} \rangle$ as a function of σ for various H_0 values (5, 10, 15, 20, and 25 mT) for maghemite; (b) $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ as a function of σ for various H_0 values (5, 10, 15, 20, and 25 mT) for maghemite. In these simulations, f, mD, and H_s were assumed to be 300 kHz, 20 nm, and 0 mT, respectively.

monotonically with increasing σ value in the case of magnetite (Fig. 10). The dependency of $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ on H_s differed between maghemite (Fig. 9(b)) and magnetite (Fig. 10(b)).

Fig. 11 shows the (SLP_{qss}) values as a function of the distance from a field-free point (*x*) for various σ values (0, 0.1, 0.2, 0.3, and 0.4). Fig. 11(a) and Fig.

IV.DISCUSSION

We previously investigated methods for estimating the SLP in magnetic hyperthermia under various conditions of MNPs and AMF [8]. We also presented a method for the estimation of the SLP in the presence of both the AMF and SMF [11], which was derived by solving the magnetization relaxation equation of Shliomis [12] numerically. In these studies, we assumed that the particle size distribution was monodisperse. As previously described, however, the existence of some size polydispersity of MNPs is experimentally unavoidable [13], [14]. Thus, in this study, we investigated the effect of the particle size polydispersity on the SLP in magnetic hyperthermia under various conditions of MNPs, AMF, and SMF. Our results (Fig.3 to Fig.11)demonstrated that the SLP



Fig. 6:(a) $\langle SLP_{qss} \rangle$ as a function of σ for various H_0 values (5, 10, 15, 20, and 25 mT) for magnetite; (b) $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ as a function of σ for various H_0 values (5, 10, 15, 20, and 25 mT) for magnetite. In these simulations, f, mD, and H_s were assumed to be 300 kHz, 20 nm, and 0 mT, respectively.

11(b) show cases for maghemite and magnetite, respectively. In these simulations, H_0 , f, mD, and G_s were assumed to be 20 mT, 300 kHz, 20 nm, and 2 T/m, respectively. As shown in Fig. 11, the plot of $\langle SLP_{qss} \rangle$ against x changed largely depending on σ in both cases and its dependency on σ differed between maghemite (Fig. 11(a)) and magnetite (Fig. 11(b)).

in magnetic hyperthermia largely depends on the particle size polydispersity, and suggest that it is essential to take into account the particle size polydispersity for the accurate estimation of SLP in magnetic hyperthermia.

In this study, we assumed that the particle size distribution obeys a log-normal distribution. As previously described, this assumption is commonly used and appears to be reasonable [17].

The derivative of $\langle SLP_{qss} \rangle$ with respect to *D* given by Eq. (19), *i.e.*, $d\langle SLP_{qss} \rangle/dD$ appears to represent the sensitivity of $\langle SLP_{qss} \rangle$ to *D*. As shown in Fig. 2, although *mD* was assumed to be 20 nm, the peak of $d\langle SLP_{qss} \rangle/dD$ was shifted to the larger *D*side in the case of maghemite (Fig. 2(a)), whereas that for magnetite had a peak near *D*=20 nm (Fig. 2(b)). As



Fig. 7:(a) $\langle SLP_{qss} \rangle$ as a function of σ for various f values (200, 400, 600, 800, and 1000 kHz) for maghemite; (b) $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ as a function of σ for various f values (200, 400, 600, 800, and 1000 kHz) for maghemite. In these simulations, H_0 , mD, and H_s were assumed to be 20 mT, 20 nm, and 0 mT, respectively.

previously described, the height of the peak decreased with increasing σ value in both cases. Furthermore, the plot of $d\langle SLP_{qss} \rangle/dD$ against *D* for maghemite (Fig. 2(a)) was broader than that for magnetite (Fig. 2(b)). The height and width of these plots may be helpful in designing and/or synthesizing MNPs suitable for magnetic hyperthermia.

As shown in Fig.3andFig. 4. the dependencies of (SLP_{qss}) and $(SLP_{qss})/SLP_{qss}^{mono}$ on σ changed largely depending on mD. In the case of maghemite (Fig. 3), when mDwas 25 nm, both (SLP_{qss}) and $(SLP_{qss})/SLP_{qss}^{mono}$ decreased almost monotonically with increasing σ value. When mD deviated from 25 nm, they increased with increasing σ value, making peaks, and then decreased thereafter. In the case of magnetite (Fig. 4), when mD was 20 nm, both (SLP_{qss}) and $(SLP_{qss})/SLP_{qss}^{mono}$ decreased almost monotonically with increasing σ value, whereas they had peaks when mD deviated from 20 nm. The mD values of 25 nm for maghemite and 20 nm for magnetite approximately correspond to D at which $d(SLP_{ass})/dD$ has a peak (Fig. 2). Thus, the above findings may suggest that $d(SLP_{qss})/dD$ is a useful



Fig. 8:(a) $\langle SLP_{qss} \rangle$ as a function of σ for various f values (200, 400, 600, 800, and 1000 kHz) for magnetite; (b) $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ as a function of σ for various f values (200, 400, 600, 800, and 1000 kHz) for magnetite. In these simulations, H_0 , mD, and H_s were assumed to be 20 mT, 20 nm, and 0 mT, respectively.

parameter for evaluating the effect of size polydispersity on SLP.

As shown in Fig. 5 and Fig. 6, (SLP_{ass})/SLP_{ass} did not change largely depending on H_0 . Similarly, the dependency of $(SLP_{qss})/SLP_{qss}^{mono}$ on H_s was not large (Fig. 9 and Fig. 10). As shown inFig. 7 and Fig. 8, however, $(SLP_{qss})/SLP_{qss}^{mono}$ changed largely depending on f. Furthermore, its dependency on f differed between maghemite and magnetite. H_0 and f are usually determined by considering the safety, i.e., the prevention of unwanted damage to the surrounding healthy tissue via eddy currents (typically their product $H_0 \cdot f < 5 \times 10^9$ Am⁻¹s⁻¹) [19]. The above results appear to suggest that the dependency of $(SLP_{qss})/SLP_{qss}^{mono}$ on f can also be one of the important factors in selecting f for enhancing the therapeutic efficacy of magnetic hyperthermia without unwanted damage to the surrounding healthy tissue. In other words, it might be possible to enhance the SLP in magnetic hyperthermia by controlling the particle size polydispersity depending on f.

Khandhar *et al.* [20] developed a comprehensive protocol for synthesizing highly



Fig. 9:(a) $\langle SLP_{qss} \rangle$ as a function of σ for various H_s values (0, 10, 20, 30, and 40 mT) for maghemite; (b) $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ as a function of σ for various H_s values (0, 10, 20, 30, and 40 mT) for maghemite. In these simulations, H_0 , f, and mD were assumed to be 20 mT, 300 kHz, and 20 nm, respectively.

monodispersed MNPs and experimentally investigated the effect of particle size polydispersity on overall SLP. They reported that SLP values dropped by 30% with increased size polydispersity from $\sigma = 0.175$ to $\sigma = 0.266$ and emphasized the importance of monodispersity [20]. Gonzales-Weimuller *et al.* [21] reported that higher heating rates are achievable with iron oxides by decreasing polydispersity of the ferrofluid. However, it is worth noting that the opposite trend, *i.e.*, enhancement of the heating performance with higher polydispersity, has also been reported [13],[22]. Our results suggest that both cases can occur depending on the magnetic and physical properties of MNPs and/or the parameters of AMF.

As shown in Fig. 11, the plot of $\langle SLP_{qss} \rangle$ against x changed largely depending on σ and its dependency on σ differed between maghemite and magnetite. These findings will be important in considering the control of the temperature rise and the area of local heating in magnetic hyperthermia by use of the SMF [9], [10].

In this study, we derived Eq. (13) by solving the magnetization relaxation equation of Shliomis [12] (Eq. (1)) with an assumption that there is no bulk flow and the magnetization of MNPs and magnetic field are



Fig. 10:(a) $\langle SLP_{qss} \rangle$ as a function of σ for various H_s values (0, 10, 20, 30, and 40 mT) for magnetite; (b) $\langle SLP_{qss} \rangle / SLP_{qss}^{mono}$ as a function of σ for various H_s values (0, 10, 20, 30, and 40 mT) for magnetite. In these simulations, H_0 , f, and mD were assumed to be 20 mT, 300 kHz, and 20 nm, respectively.

collinear. In this case, Eq. (1) is reduced to Eq. (2), which can be easily solved using convolution integral as shown in Eq. (9). Although Eq. (2) appears to be valid in considering the magnetic hyperthermia with small MNPs in the superparamagnetic state, it will be necessary to solve Eq. (1) without any assumptions or another magnetization equation derived microscopically from the Fokker-Planck equation [15] for more detailed analysis. Dhavalikar et al. [23] used the phenomenological magnetization equation derived by Martsenyuk et al. [24] instead of the Shliomis' equation [12] used in this study. The comparative studies between the present results with those obtained by the equation of Martsenyuk et al. [24] are currently in progress. Furthermore, we targeted the MNPs consisting of maghemite and magnetite with the magnetic and physical properties described in the "Simulation Studies" section. We will also perform further studies for the MNPs with other magnetic and physical properties and/or other MNPs.

In this study, we investigated the effect of particle size polydispersity on the heating performance of MNPs from a global point of view. For more detailed analysis, it might be necessary to investigate it at a local level using methods such as a Monte Carlo



Fig. 11:(a) $\langle SLP_{qss} \rangle$ as a function of the distance from a field-free point (x) for various ovalues (0, 0.1, 0.2, 0.3, and 0.4) for maghemite; (b) $\langle SLP_{qss} \rangle$ as a function of x for various of values (0, 0.1, 0.2, 0.3, and 0.4) for magnetite. In these simulations, H_0 , f, mD, and the gradient strength of a static magnetic field (G_s) were assumed to be 20 mT, 300 kHz, 20 nm, and 2 T/m, respectively.

technique [13], [14]. Studies using the Monte Carlo technique are currently planned.

V. CONCLUSIONS

We investigated the effect of particle size polydispersity on the SLP in magnetic hyperthermia in comparison with the monodisperse case under various conditions of MNPs, AMF, and SMF. Our results demonstrated that the particle size polydispersity largely affects the SLP in magnetic hyperthermia and suggest that it is essential to take it into account for the accurate estimation of SLP and for accurately controlling the temperature rise and the area of local heating in magnetic hyperthermia using the SMF.

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